Instruction Manual

TD200 TEMPERATURE CONTROLLER INSTRUCTION MANUAL Version 1.4

1. Overview

This controller can be used for solar water heater control and drying oven control. It has two sensor inputs. The temperature difference between the two sensors (DT) is used for output control. The controller has two independent outputs also. One of the output is to controller a cooling device so that DT is limited to a specified range. The other output is for a heating device so that DT is maintained to be not less than a specified range.

This controller is a plug and play controller. No wiring is needed for the heater or cooler. Both the heating and cooling control modes are simple on/off control, similar to a mechanical thermostat but with much higher precision due to adjustable hysteresis band, precise sensor and digital read out. Anti-short function is provided for cooling to protect the compressor from being turned on with high pressure Freon.

Different operation temperature ranges of the two outputs can be set separately. Once the cooling range is set, the controller program will automatically limit the heating range to prevent both heating and cooling from being turned on at the same time.

Two digital silicon band gap sensors are used. The advantage is being much more reliable in moisture environment than thermistor sensor. They can be immersed over extended period of time. They also has a more uniform accuracy over an entire specified temperature range.

2. Specification

-99~170 °C, -99~306 °F
0.1 °C (between -9.9 ~ 99.9 °C)
1 °C (between -99 ~ -10 °C,100~170°C)
0.1 °F (between -9.9~99.9 °F)
1 °F (between -99 ~ -10 °F,100 ~306 °F)
0.5 °C or 0.9 °F
On/Off Control. Heating and Cooling
10A, 120V or 240V AC *
High and Low Limit
Silicon Band Gap Sensor
0.25" OD (6.35 mm) x 1" (25mm) long
-55~125 °C(-67°F to +257°F)
91×140×46mm
85 ~242VAC, 50Hz/60Hz
3 ft (1m)
3 ft (1m)
1 Year

3. Front Panel

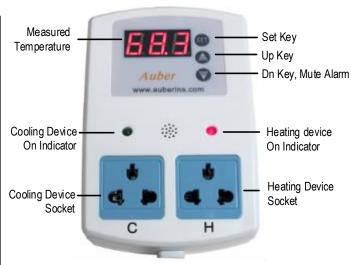


Figure 1. Front Panel

4. Setup Flow Chart

During the normal operation, the controller offers three different displaying modes: temperature reading of Sensor 1, T1; temperature reading of sensor 2, T2; or, the temperature difference between the two sensors, DT.

Following chart shows how to change the display from one reading to the other.

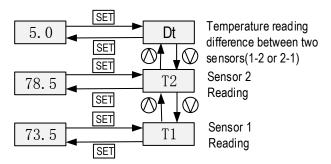


Figure 2 Probe reading Flow Chart

Press SET key momentarily. the controller will show Dt . Press Down key will show T2 . Press down key again, the controller will show T1 . Press SET when T1 is displayed will set the controller to display the Sensor 1 temperature. Press SET when DT is displayed will set the controller to display the differential temperature. Press SET when T2 is displayed will set the controller to display the Sensor 2 temperature.

If T1 is selected before the controller was powered off, it will display the T1 next time when powered up.

If either of the temperature sensors fails, the controller will display "Err".

5. Parameter Settings

To change the target temperature and system parameters, press SET key for 5 seconds, the controller will enter the parameter set up mode. The first parameter CSP will show on the display. Press SET key again to see the initial setting. Use Up or Down key to modify the parameter value. Then press SET key to confirm the change. The display will show the parameter again. Press down key to show the next parameter. The instrument will automatically exit if no key is pressed for 10 seconds. Please see Following flow chart on parameter settings and table 1 for the parameter definitions.

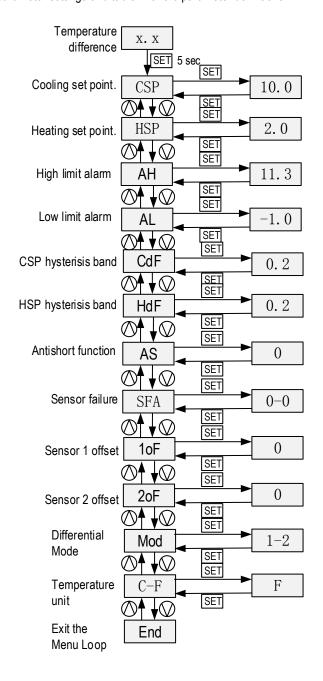


Figure 3 Parameter setting Flow Chart

Table 1. Parameters Description

CSP CSP Cooling Set Point -99~306 °F -99~CSP °F -99~CSP °F -99~CSP °C 10.0 HSP HSP Heating Set Point -99~CSP °C -99~CSP °C -99~306 °F -99~306 °F -99~170 °C -1.0 11.3 AH AH AH Alarm High Limit -99~AH °F -99~AH °F -99~AH °C -1.0 -1.0 CdF CDF Cooling Differential 0~50.0 0.2 HdF HDF Heating Differntial 0~50.0 0.2 AS AS Cooling Antishort 0~12 min 0 AS AS Sensor Failure Operation 0-0, 0-1, 1-0 0-0 4 10F 10F sensor 1 offset -10~10 0 5 20F 20F sensor 2 offset -10~10 0 5 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 C-F C-F °C and °F temperature unit coversion C: Celsius F:Fahrenheit F:Fahrenheit	Code		Description	Setting range	Initial	Note
HSP HSP	CSP	CSP	Cooling Set Point		10.0	,
AH AH Alarm High Limit -99~170 °C 11.3 AL AL Alarm Low Limit -99~AH °F -1.0 CdF CDF Cooling Differential 0~50.0 0.2 HdF HDF Heating Differential 0~50.0 0.2 AS AS Cooling Antishort 0~12 min 0 AS AS Cooling Antishort 0-0, 0-1, 1-0 0-0 SFA SFA Sensor Failure Operation 0-0, 0-1, 1-0 0-0 4 1oF 1OF sensor 1 offset -10~10 0 5 2oF 2OF sensor 2 offset -10~10 0 5 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 6 C-F C-F C-F and °F temperature unit coversion C: Celsius F: Fahrenheit F: Fahrenheit	HSP	HSP	Heating Set Point		2.0	'
AL AL Alarm Low Limit -99~AH °F -1.0 CdF CDF Cooling Differential 0~50.0 0.2 HdF HDF Heating Differntial 0~50.0 0.2 AS AS Cooling Antishort 0~12 min 0 SFA SFA Sensor Failure Operation 0-0, 0-1, 1-0 0-0 4 1oF 1OF sensor 1 offset -10~10 0 5 2oF 2OF sensor 2 offset -10~10 0 0 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 6 C-F C-F C-F and °F temperature unit coversion C: Celsius F: Fahrenheit F	АН	АН	Alarm High Limit		11.3	2
HdF HDF	AL	AL	Alarm Low Limit	55 7	-1.0	2
AS AS Cooling Antishort 0~12 min 0 3 SFA SFA Sensor Failure Operation 0-0, 0-1, 1-0 0-0 4 1oF 1OF sensor 1 offset -10~10 0 2oF 2OF sensor 2 offset -10~10 0 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 C-F	CdF	CDF	Cooling Differential	0~50.0	0.2	. 1
SFA SFA Sensor Failure Operation 0-0, 0-1, 1-0 0-0 4 1oF 1OF sensor 1 offset -10~10 0 5 2oF 2OF sensor 2 offset -10~10 0 0 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 6 C-F C-F C-F cand °F temperature unit coversion C: Celsius F:Fahrenheit F	HdF	HDF	Heating Differntial	0~50.0	0.2	·
1oF 1OF sensor 1 offset -10~10 0 5 2oF 2OF sensor 2 offset -10~10 0 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 C-F C-F C-F cond of temperature unit coversion C: Celsius F: Fahrenheit F	AS	AS	Cooling Antishort	0~12 min	0	3
2oF 2OF sensor 2 offset -10~10 0 Mod MOD Differential Mode 1-2 or 2-1 1-2 6 C-F C-F C-F C-F coversion C: Celsius F:Fahrenheit F	SFA	SFA	Sensor Failure Operation	0-0, 0-1, 1-0	0-0	4
Mod MOD Differential Mode 1-2 or 2-1 1-2 6 C-F C-F Coversion F:Fahrenheit	1oF	10F	sensor 1 offset	-10~10	0	5
C-F C-F °C and °F temperature unit C: Celsius F:Fahrenheit F	2oF	20F	sensor 2 offset	-10~10	0	
C-F C-F coversion F:Fahrenheit F	Mod	MOD	Differential Mode	1-2 or 2-1	1-2	6
End END exit the menu loop	C-F	C-F	'		F	
	End	END	exit the menu loop			

Note 1. CSP is the set point for the cooling control channel. HSP is the set point for the heating control channel. The value of the setting is the temperature reading difference between the two probes. The unit is degree (Celsius or Fahrenheit, depends on the setting). The relay for the cooling channel control output will be on when the temperature difference is larger than the CSP. The relay for the heating channel will be on when the temperature difference is smaller than the HSP. For example, HSP=5 means the controller will try to keep the sensor 1 temperature reading 5 degrees different from the sensor 2 temperature reading, regardless the actual temperature reading of sensor 1 or sensor 2 (as long as the both sensor are within their working temperature range). The cooling channel can be used for controlling the solar water heater pump. The heating channel can be used for controlling a dryer.

When DT is larger than CSP, C channel turns on. When DT is smaller than HSP, H channel turns on. Please note, HSP has to be smaller than CSP so that two channel dose not work against each other. For example, when CSP=20.0 °F, HSP can be set to any value between -99 and 20.0. For CSP, it can be set to any value between

-99 and 306(°F). If you set CSP to 55.0, the HSP will be set to 55.0 automatically.

CDF is the differential band (hysteresis band) between cooling set point and on/off temperature. The controller will turn on when DT > CSP+CDF and turn off when DT < CSP-CDF. For example, if CSP=20.0°F, CDF=0.2, the controller will turn on when DT>20.2°F and turn off when DT<19.8°F. Similarly, HDF is the differential band (hysteresis band) between heating set point and on/off temperature.

The controller will turn off at when DT>HSP+HDF and turn on again when DT < HSP-HDF. For example, if HSP= 18°F, HDF=0.2, the controller will turn off when DT>18.2 °F and turn on when DT<17.8°F.

Small differential band gives tight control; large differential band reduces the frequency of cycle on and off. It will extend the life of relay and compressor.

Note 2. The value of the alarm setting, AH and AL are for the maximum and minimum temperature difference between the two probes, not the actual temperature reading of the probes. If the actual temperature reading of either probe is out of its working temperature range, the controller will display error and trigger the alarm buzzer also. When DT is larger than AH, alarm buzzer will be on and display will flash AH and normal display. When DT is smaller than AL, alarm buzzer will be on. And display will flash between AL and the normal display. Alarm can be cancelled by press V key. The alarm will not turn on until DT re-enter the alarm zone after it returned to the normal range once. To disable the alarm, set AH=AL.

The maximum value of the AL can be set is the current value of AH. But AH can be set to the value between -99~306°F or -99~170 °C. When AH is set to a value lower than current AL, the AL will be adjusted to the AH value automatically.

For example, when AH=95.0 $^{\circ}$ F, AL can be set to any value between -58 and 95.0. For AH, it can be set to any value between -99 and 306. If you set The AH to 25.0, the AL will be set to 25.0 automatically.

Note 3. The Cooling Antishort is the delay the time to turn the cooling load on . when the controller is used for cooling and load is a compressor, it should not turn on the compressor when it is at high pressure (just after turned off). Otherwise, It may shorten the life of compressor. The Anti-Short cycle delay function can be used to prevent the rapid cycling of the compressor. It establishes the minimum time that the NO contacts remains open (after reaching cutout) before closing again. The delay overrides any Load Demand and does not allow the NO contacts to close until the set time-delay value has elapsed. It gives time to release the refrigerant pressure through evaporator. It is typically set to 4-6 (minutes).

Note 4. The SFA defines how the output would be if the sensor fails. It can be set to 0-0, 0-1 or 1-0. Please refer to table 2 for details.

Table 2. Output of the controller when sensor fails:

SFA	Controller output when sensor fails
0-0	cooler off, heater off
1-0	cooler on, heater off
0-1	cooler off, heater on

For example, when the unit controls a refrigerator for food, you may want to set the TSF to ON if the sensor fails to keep the food cold. When it controls a heater, you may want to set the output to OFF for safety purpose.

Note 5. The offset is used to set an input offset to compensate the error produced by the sensor or input signal itself.

For example, for temperature, if sensor 1 displays 37 $^{\circ}$ F when the actual temperature is 32 $^{\circ}$ F, setting parameter 10F = - 5 will make the controller display 32 $^{\circ}$ F.

Note 6. The differential mode can be set to 1-2 or 2-1. It defines the how the value of DT is calculated. For example, 1-2 means DT is equal to the reading of sensor 1 minus reading of sensor 2.

6. How to install the sensor to the unit.

The connector of sensor contains a slot for correct pin connection. It also has a spring lock to prevent disconnections from accidental pulling on the cable. To install the to the unit, please align the slot of the female connector on the sensor to the red mark of the male connector on the unit, then hold the tail and push the female connector forward. To remove the connector, please pull the spring loaded collar of the female connector. Please see the Figure 4 and Figure 5 below for details.



Figure 4. Install the Sensor



Figure 5. Remove the Sensor

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